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2016 J. Phys.: Conf. Ser. 678 012049
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Fully gauge-invariant maximally path-dependent gluon TMD: Coordinate representation

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Abstract. We propose an approach to obtain gauge-invariant maximally path-dependent operator definition of the gluon transverse-momentum dependent distribution function (gTMD). We demonstrate that the evolution equations for the gTMD can be derived from the shape-variation integral-differential equations formulated in the coordinate space.

1. Introduction

Transverse-momentum dependent (unintegrated) parton density functions (TMD pdfs in what follows) extent the idea of collinear (integrated) pdfs, which absorb mass singularities in any order of perturbative expansion, making it possible to apply the QCD factorisation approach to the inclusive hadron processes ($e^+e^-$ to hadrons, DIS) [1]. In more exclusive cross-sections, which one deals with in the semi-inclusive reactions (semi-inclusive DIS, Drell-Yan, Higgs, vector boson, heavy-flavour production) factorisation often implies intrinsic transverse-momentum dependence of non-perturbative pdfs, which must be constructed in such a way to absorb not only mass, but also rapidity singularities [2, 3, 4, 5, 6]. With TMD pdfs one gets access to the three-dimensional structure of the nucleon in the momentum space, which is actively investigated in ongoing and planned experiments at the LHC, JLab + JLab 12 GeV upgrade, RHIC, EIC etc., providing an incentive to the rapid theoretical progress in the field (see, e.g., [7, 8] and Refs. therein).

As compared to the quark TMD case, the gauge-invariant gluon TMD exhibits much more involved structure of the gauge links (Wilson lines), so that the path-dependence brings about extra complications to the understanding of (non-)universality of the TMD pdfs. On the other hand, this path-dependence allows us to manipulate freely with the gauge links entering the operator definition of the gTMD. In the present paper we develop a quantum-field theoretic approach to the definition of the gluon TMD (gTMD) making use of the arbitrariness of the trajectories of the Wilson lines to formulate evolution of the gTMD in terms of the equations of motion in the so-called generalized loop space, which elements are the hadronic matrix elements of the arbitrary Wilson loops.

2. Operator structure of TMD pdfs

Following the standard approach one derives the operator definitions of the various TMD pdfs starting with the factorisation of a given process in a convenient gauge, which yields an obviously gauge-dependent pdf, such as
\[ G_{\mu\nu}(k; P, S) = \int d^4z \ e^{-ikz} \langle h | A^{\mu}(z) A^{\nu}(0) | h \rangle, \] (1)

that is a hadronic matrix element, which corresponds to the distribution of the gluons with momentum \( k \) inside the hadron \( h \) with momentum \( P \) and spin \( S \) \[2, 9\]. Summing up collinear gluon contributions yields a gauge-invariant pdf supplied with the Wilson lines, whose path \( \gamma \) is determined by the factorisation scheme:

\[ G_{\mu\nu|\rho\sigma}(k; P, S) = \int d^4z \ e^{-ikz} \langle h | F^{\mu\nu}(z) \mathcal{W}_{\gamma} F^{\rho\sigma}(0) | h \rangle, \] (2)

where the field strength is defined in the adjoint representation

\[ F^{\mu\nu} = \partial^\mu A^\nu - \partial^\nu A^\mu - ig[A^\mu, A^\nu], \quad F_{\mu\nu} = F^{a}_{\mu\nu} T^a. \] (3)

Generic gauge-invariant \( gTMD \) c bean obtained by integrating over the minus-light-cone component of the partonic momentum and projecting onto the transverse Lorentz indices:

\[ G^{ij}(x, k; P, S) \sim \int dk^- G^{+i+j}(k; P, S) = \int dz^- d^2z_\perp e^{-ikz} \langle h | F^{+i}(z) \mathcal{W}_{\gamma} F^{+j}(0) | h \rangle, \] (4)

(5)

Let us explore a possibility of an alternative approach to the definition of the TMD pdfs. We construct first a generic fully gauge-invariant (by construction) and maximally path-dependent object consisting of the Wilson lines/loops defined on the set of absolutely arbitrary trajectories \( \gamma \):

\[ \mathcal{W}_{\gamma} = \mathcal{P}_\gamma \exp \oint_{\gamma} d\zeta A^\mu(\zeta). \] (6)

So far we do not assume any factorisation scheme and even do not identify the processes to which those objects are supposed to be applicable. Given the arbitrariness of the paths, one is able to adjust them to a specific factorisation scheme by performing the evolution in the coordinate space. Hence we end up with an object which can be further associated with a realistic gauge-invariant TMD pdf.

3. Equations of motion in the loop space

Shape variations (or evolution in the coordinate representation) of arbitrary Wilson loops can be consistently formulated in terms of the equations of motion in the loop space, that is the integral-differential equations which the elements of this space (Wilson loops) obey, if the underlying contours \( \gamma_i \) on which the path-ordered exponentials of the gauge fields are defined experience certain infinitesimal local variations. The variations of the contours give rise to the variations of the exponentials themselves, the latter being described by the infinite set of the Makeenko-Migdal loop equations \[10, 11, 12, 13, 14, 15\]. More specifically, the elements of the loop space are the vacuum matrix elements of products of the Wilson loops, that is

\[ \langle 0 | \mathcal{W}_{\gamma_1} \cdots \mathcal{W}_{\gamma_n} | 0 \rangle = \langle 0 | \mathcal{W}_{\gamma_1} \cdots \mathcal{W}_{\gamma_n} | 0 \rangle \] (7)

These fundamental gauge-invariant (by construction) degrees of freedom obey the Makeenko-Migdal loop equations (in the large-\( N_c \) limit)

\[ \partial^\nu \frac{\delta}{\delta \sigma_{\mu\nu}(x)} \langle 0 | \mathcal{W}^1_{\gamma} | 0 \rangle = N_c g^2 \oint_{\gamma} dz^\mu \delta^{(4)}(x-z) \langle 0 | \mathcal{W}^2_{\gamma x} | 0 \rangle, \] (8)

where the area and path differential operators are defined as follows \[10, 11, 12\]:
Area derivative describes the behaviour of the Wilson loop under the infinitesimal variations of the area \( \delta \sigma_{\mu\nu}(z) \) at a given point

\[
\frac{\delta}{\delta \sigma_{\mu\nu}(z)} \langle 0 | W(0) | 0 \rangle = \lim_{|\delta \sigma_{\mu\nu}(z)| \to 0} \frac{\langle 0 | W(0) \delta_{\gamma_{\gamma_{\gamma}}(z)} | 0 \rangle - \langle 0 | W(0) | 0 \rangle}{|\delta \sigma_{\mu\nu}(z)|} \tag{9}
\]

Path derivative deals with the infinitesimal path extensions and contractions \( \delta z^{-1}_\mu \delta z_\mu \) at a given point

\[
\partial_\mu \langle 0 | W(0) | 0 \rangle = \lim_{|\delta z_\mu| \to 0} \frac{\langle 0 | W(0) \delta_{\gamma_{\gamma_{\gamma}}(0)} | 0 \rangle - \langle 0 | W(0) | 0 \rangle}{|\delta z_\mu|} \tag{10}
\]

These differential operators in the loop space determine the evolution of the Wilson loops in the coordinate representation. In other words, starting from a loop having a given shape, one can come to a loop with another shape by solving the above evolution equations. This is exactly what is needed to adjust a generic Wilson loop to some specific geometrical layout prescribed by a factorisation framework.

4. Stokes-Mandelstam gluon TMD

Let us show how this strategy can be practically implemented. Consider first the Wilson loops themselves, not their matrix elements. This is needed since we want to work with the hadronic matrix elements, not with the vacuum ones. Making use of non-Abelian Stokes’ theorem

\[
\mathcal{P}_\gamma \exp \oint_{\gamma} d\zeta A^\mu(\zeta) = \mathcal{P}_\gamma \mathcal{P}_\sigma \exp \int_\sigma d\sigma_{\mu\nu}(\zeta) \mathcal{F}^{\mu\nu}(\zeta) \tag{11}
\]

and the Mandelstam formula

\[
\frac{\delta}{\delta \sigma_{\mu\nu}(x)} \mathcal{P}_\gamma \exp \oint_{\gamma} d\zeta A^\mu(\zeta) = \mathcal{P}_\gamma \mathcal{F}^{\mu\nu}(x) \exp \oint_{\gamma} d\zeta A^\mu(\zeta), \tag{12}
\]

we see that the generic correlation function (2) can be represented in the following form

\[
\tilde{G}^{\mu\nu|\sigma\sigma}(z; P, S) = \frac{\delta}{\delta \sigma_{\mu\nu}(z)} \frac{\delta}{\delta \sigma_{\mu\nu}(0)} \langle h | W_{\gamma_{\gamma_{\gamma_{\gamma}}}(z)} | h \rangle \tag{13}
\]

\[
= \frac{\delta}{\delta \sigma_{\mu\nu}(z)} \frac{\delta}{\delta \sigma_{\mu\nu}(0)} \sum_X \langle h | W_{\gamma_{\gamma_{\gamma}}(z)} | X \rangle \langle X | W_{\gamma_{\gamma_{\gamma_{\gamma}}}(0)} | h \rangle. \tag{14}
\]

We coin this representation the *Stokes-Mandelstam* gTMD definition. The key feature of this definition (and of the entire approach) is that one first calculates the hadronic matrix element of an arbitrary Wilson loop

\[
\langle h | W_{\gamma_{\gamma_{\gamma}}(z)} | h \rangle
\]

choosing its shape the most convenient for the practical purposed. In particular, in the situations where the non-Abelian exponentiation is applicable

\[
\langle h | W_{\gamma_{\gamma_{\gamma}}(z)} | h \rangle = \exp \left[ \sum a_n W^{(n)} \right], \quad W^{(n)} = \text{hadronic correlators}, \tag{15}
\]

one can even obtain an explicit expression for this matrix element and thereafter evaluate the area derivatives in terms of the fundamental hadronic correlation functions. The latter can be taken, for instance, from lattice simulations. Let us illustrate the use of this framework by a simple Abelian example.
4.1. Example: Abelian exponentiation

Wilson loops in the Abelian gauge theory are known to exponentiate

\[ \langle h | W_\gamma | h \rangle = \exp \left[ -\frac{g^2}{2} \oint \gamma d\tau \int_\gamma d\tau' D_{\mu\nu}(\tau - \tau') \right] \tag{16} \]

where the basic hadronic correlator reads

\[ D_{\mu\nu}(\zeta - \zeta') = \langle h | P \gamma A_\mu(\zeta) A_\nu(\zeta') | h \rangle. \tag{18} \]

For the sake of simplicity, let us consider a spinless hadron, which entails the following parameterisation of the basic correlator (18)

\[ D_{\mu\nu}(z) = g_{\mu\nu} D_1(z, P) + \partial_\mu \partial_\nu D_2(z, P) + \{ P_\mu \partial_\nu \} D_3(z, P) + P_\mu P_\nu D_4(z, P). \tag{19} \]

Given this representation and the exponentiation, the area derivative can be evaluated straightforwardly

\[ \frac{\delta}{\delta \sigma_{\mu\nu}(z)} \langle h | W_\gamma | h \rangle = -\frac{g^2}{2} \left[ \oint \gamma d\tau \int_\gamma d\tau' \left( \partial^2 D_1(z, P) + (P \partial)^2 D_4(z, P) \right) \right] \langle h | W_\gamma | h \rangle. \tag{20} \]

After taking the path derivative \( \partial_\nu \), the non-vanishing terms are

- the standard ‘Makeenko-Migdal’ term:
  \[ \oint \gamma d\tau \partial^2 D_1(z, P) \tag{21} \]

- the hadron momentum-dependent term, obviously absent in the loop space with vacuum matrix elements
  \[ \oint \gamma d\tau \left( P \partial \right)^2 D_4(z, P) \tag{22} \]

Therefore, the shape evolution equation for the hadronic Wilson loops in the Abelian gauge theory is given by

\[ \frac{\partial^2}{\partial \tau^2} \frac{\delta}{\delta \sigma_{\mu\nu}(z)} \langle h | W_\gamma | h \rangle = -\frac{g^2}{2} \left[ \oint \gamma d\tau \partial^2 D_1(z, P) + (P \partial)^2 D_4(z, P) \right] \langle h | W_\gamma | h \rangle. \tag{23} \]

Taking into account that for the vacuum matrix elements

\[ \partial^2 D_1(z) = -\delta^{(4)}(z), \]

and that \( D_4 = 0 \) in vacuum, one easily re-obtains the Makeenko-Migdal equation in the leading order.

To conclude, we proposed a new definition of the generic gluon TMD, which allows us to work directly with the entirely gauge-invariant and maximally path-dependent hadronic matrix elements before introducing relevant gluon TMD. All necessary information is absorbed in the basic hadronic correlator (18) and the evolution equation (24) generalises the Makeenko-Migdal equation for the Abelian gauge theory to the case of the ‘hadronic’ loop space.

Further progress will be presented in a separate work [16].
Acknowledgments
The work is supported by the Belgian Federal Science Policy Office. Fruitful discussions with T. Mertens, P. Taels and F. Van der Veken are gratefully appreciated.

References