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10 RH: Rutten et al. • Wild Boar Damage Assessment

11 **Assessing Agricultural Damage by Wild Boar Using Drones**

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27 **ABSTRACT** In Flanders (northern Belgium), wild boar (*Sus scrofa*) returned in 2006 after 50
28 years of absence and the population is increasing, both in abundance and geographic extent.
29 In the absence of wild boar, Flanders' landscape structure changed into a dense, mosaic-like
30 pattern of agricultural, natural and urban areas. The return of the wild boar increasingly leads
31 to human–wildlife conflicts, mainly linked to damage in agriculture. Hence, there is a
32 growing need for a time-efficient, standardized, and accurate method to assess crop damage.
33 We present an Unmanned Aerial Vehicle–based method, using Geographic Object-Based
34 Image Analysis and Random Forests to estimate the damaged area and associated yield losses,
35 between 2015 and 2017, due to wild boar in individual fields in Flanders. Our approach
36 resulted in an 84.50% overall accuracy in calculating damaged area for maize fields and
37 94.40% for grasslands. Damage levels ranged between 14.3% and 20.2% in maize fields and
38 16.5% to 25.4% in grasslands. Our method can provide objective base data for a
39 compensation schemes and guide management strategies based on damage assessments.
40 **KEY WORDS** Belgium, crop damage, GEOBIA, Geographic Object-Based Image Analysis,
41 UAV, wildlife damage.

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44 Wild boar (*Sus scrofa*) is one of the most widespread mammal species of the world (Massei
45 and Genov 2004, Keuling et al. 2018) with populations expanding throughout Europe since
46 the 1960s (Saez-Royuela and Telleria 1986, Bieber and Ruf 2005, Acevedo et al. 2007,
47 Massei et al. 2015). Expanding abundance of wild boar is challenging for both conservation
48 (Barrios-Garcia and Ballari 2012) and society because human–wildlife conflicts arise linked
49 to damage to crops (including rooting of grasslands), traffic collisions, and disease
50 transmission (Bieber and Ruf 2005, Treves et al. 2006, Amici et al. 2012, Morelle et al. 2013,

51 Massei et al. 2015). In Flanders (northern Belgium), where wild boar was absent for more
52 than half a century, the species returned in 2006 and its population is increasing rapidly
53 (Scheppers et al. 2014). During the past few decades, landscapes in Flanders have changed
54 dramatically due to urbanization, agricultural intensification, and fragmentation. Flanders has
55 become one of the most densely populated areas in Europe: 462 persons/km² (Linell et al.
56 2001, FOD Economie, unpublished report). A fragmented structure with a mosaic-like pattern
57 composed of small natural areas, forest remnants, agricultural areas, and urbanized areas,
58 which are all crossed by a dense road network (5.2 km/km²), characterizes the landscape. This
59 results in a situation with frequent wildlife–human interactions and wildlife-related impacts
60 that warrant management attention (Riley et al. 2003).

61 Like many countries and regions in Europe, crop damage by wild boar is not
62 monitored in Flanders and no compensations are paid. Therefore, we lack knowledge on the
63 current extent of crop damage and associated losses for the agricultural sector. Yet, the
64 magnitude of crop damage by wild boar can be significant as shown in some surrounding
65 countries and regions (Schley et al. 2008 for Luxembourg, Carnis and Facchini 2012 for
66 France, Faunafonds 2014 for the Netherlands, Widar and Luxen 2016 for Wallonia).
67 However, assessments are done by a variety of methods because currently no well-established
68 and accepted method exists to assess damage in an accurate and objective manner (Michez et
69 al. 2016). Moreover, farmers who are the most affected stakeholders report an increasing need
70 for monitoring crop damage by wild boar. Consequently, there is a need for a standardized
71 monitoring of crop damage by wild boar.

72 Any methods to assess crop damage should be standardized, objective, accurate, time-
73 efficient, allow a full assessment, and applicable to different crops. Existing methods include
74 ground visits with visual assessment, mapping damage spots with handheld Global
75 Positioning System (GPS; Engeman et al. 2007a, Felix et al. 2014), and estimations

76 extrapolated from randomly selected transects or plots (Cushman et al. 2004, Chavarria et al.
77 2007, Engeman et al. 2007b). These approaches do not meet all of the desired requirements
78 because they are either time-consuming, subjective, or unsuitable for larger areas. A suitable
79 method should be able to provide data both for damage compensation schemes and modeling
80 socio-economic impacts of competing management strategies (Reyns et al. 2018).

81 The advantage of using photographs to assess rooting by wild boar was been shown by
82 Engeman et al. (2016), who took photographs of damaged grasslands in the mountainous
83 landscape of Romania from vantage points and assessed damaged area using Geographic
84 Information System by manually outlining rooted areas. Although they showed this method to
85 be quick and efficient, it can only be used in mountainous areas; but, they suggested that this
86 method could also be applied using drones. The use of camera-equipped Unmanned Aerial
87 Vehicles (UAV), “drones” might indeed offer a practical solution. In recent years, use of
88 drones has strongly increased because of easier access, flexible data-acquisition possibilities
89 and reduced costs (Salami et al. 2014). Drones offer continuous coverage, collect data at
90 centimeter resolution, require little training to operate, and can be deployed at short notice.
91 Michez et al. (2016) and Kuželka and Surový (2018) recently showed how drones can be used
92 to assess crop damage by wild boar in maize (corn) and wheat fields using generated
93 photogrammetric digital elevation models from aerial photographs taken with a drone, where
94 a threshold in height difference allowed them to distinguish damaged from undamaged crops.
95 However, Michez et al. (2016) also outlined that this method is less applicable to crop types
96 where damage does not involve height difference like grasslands. A manual delineation would
97 be more applicable in croplands, but this is not objective and involves a time-consuming
98 procedure. Therefore, an automated processing flow is desired (Engeman et al. 2016).
99 Geographic Object-Based Image Analysis (GEOBIA), in which pixels are grouped into
100 informative objects (i.e., coherent landscape elements; (Blaschke 2010, Addink et al. 2012), is

101 a technique that can be used as a standardized semiautomated method for interpretation of
102 aerial photographs (Addink et al. 2010, Blaschke et al. 2014, Vogels et al. 2017). Geographic
103 Object-Based Image Analysis has been shown to be useful in assessing the severity of crop
104 damage by insects on sorghum crops (Puig et al. 2015) and mapping cane grub (*Dermolepida*
105 *albohirtum*) damage on sugarcane plants (Johansen et al. 2014, 2017). We investigated
106 whether GEOBIA can be an appropriate technique to analyze aerial photos of fields damaged
107 by wild boar in an accurate and semiautomated workflow.

108 We developed a semiautomated workflow to assess crop damage at the field level on
109 UAV imagery. Our objectives were 1) assessing the accuracy with which crop damage can be
110 calculated using GEOBIA; 2) assessing the variation of damaged area in damaged fields; and
111 3) assessing the time- and cost-efficiency of damage estimation from UAV images.

112 **STUDY AREA**

113 Flanders (northern Belgium) had a highly fragmented land cover with 11.4% forest coverage
114 and 53% agricultural coverage (Demolder et al. 2014). The distribution of wild boar in
115 Flanders was largely limited to the eastern province of Limburg and some eastern
116 municipalities in the province of Antwerp (Scheppers et al. 2014). In Limburg, the area where
117 most damages were reported by farmers was selected based on the results of an online survey
118 (Rutten et al., unpublished data; Fig. 1). Farmers within the study area could report crop
119 damage by wild boar in the scope of this research. All reported damage cases from 2015,
120 2016, and 2017 were assessed and included in this study.

121 **METHODS**

122 **Data Acquisition**

123 When farmers reported crop damage by wild boar, we photographed the damaged field using
124 a UAV (DJI Phantom 3 Advanced using default included camera: 12 megapixel, f/2.8, 94°
125 field of view; DJI, Shenzhen, China) just before harvesting maize fields or shortly after

126 reporting damage in grasslands. Using the Pix4D Capture App (Pix4D S.A., Lausanne,
127 Switzerland) as a flight planner while flying at 40–45-m height, we took serial photos with
128 80–85% overlap between photos. Afterward we stitched photographs into a georeferenced
129 orthophoto using Agisoft Photoscan (Agisoft LLC, St. Petersburg, Russia) or ENVI
130 Onebutton (Icaros, Fairfax, VA). We clipped Individual fields from the orthophotos to
131 exclude the surrounding landscape from the analysis. In total, we photographed 133 damaged
132 fields (Excel Table S1, available online in Supporting Information).

133 **Geographic Object-Based Image Analysis**

134 *Principle.*—Geographic Object-Based Image Analysis is a technique in which
135 classification of the photographs is not based on pixels, but on objects. These represent groups
136 of neighboring pixels that are spectrally similar (Addink et al. 2010, Blaschke 2010).
137 Subsequent classification of objects is not limited to spectral information (as is characteristic
138 for pixel-based approaches) but classification can be based on information on overall color
139 and tone, texture, pattern, shape, shadow, context and size of objects (Blaschke et al. 2014).
140 This makes the workflow of GEOBIA similar to our human visual perception of the world, so
141 coherent landscape elements can be defined and used for landscape classification (Addink et
142 al. 2012). Our specific goal was to classify damaged fields into undamaged and damaged
143 areas.

144 *Image segmentation.*—Geographic Object-Based Image Analysis starts with a
145 segmentation step in which we segmented orthophotos into objects representing meaningful
146 landscape elements. We performed this segmentation using the eCognition® Developer
147 software (Trimble Inc., Westminster, CO). We grouped pixels into homogeneous objects
148 using multiresolution segmentation, which is based on a heterogeneity threshold considering
149 both spectral similarity and shape characteristics. In subsequent steps, we merged small
150 objects into larger objects until the heterogeneity threshold is reached (Benz et al. 2004). We

151 visually optimized the threshold such that the objects were as large as possible while
152 representing either damaged or undamaged crops, avoiding a combination of the 2 classes
153 (Fig. 2).

154 **Random Forest Models**

155 We performed classification of objects using the Random Forest (RF) algorithm (Breiman
156 2001) based on a set of 25 attributes describing shape (4), texture (8), and spectral properties
157 (13) of the objects (Excel Table S2, available online in Supporting Information). The Random
158 Forest is a robust classifier that makes predictions based on a training set (independent
159 variables) using multiple decision trees. Random Forests are increasingly used in land-use and
160 land-cover classifications (Rodriguez-Galiano et al. 2012). We created the Random Forests in
161 this study using the randomForest package (Liaw and Wiener 2002) available in the R
162 software environment (R Studio, Boston, Massachusetts, USA).

163 We built a RF-model separately for maize and grasslands, with the number of trees set
164 to 10.000 for each model. We initially trained the RF-models on information from the maize
165 fields and grasslands of 2016. Ideally, the RF-model would classify data from any year with
166 similar accuracy values, without the need for calibration when a new set of photos arrives.
167 When the accuracy for the 2016 RF-model was rather low (we set an arbitrary limit of 80%
168 overall accuracy, which we regarded the absolute minimum), we added fields from other
169 years (2015 and 2017) to include interannual variation because this notably influences model
170 performance. For maize fields, preliminary model building indeed showed that based on 22
171 segmented orthophotos of maize fields of 2016, model performance did not reach 80% overall
172 accuracy; therefore, we added 5 extra maize fields of 2015 and 5 of 2017 resulting in 32 total
173 fields. This was not the case for grasslands because model performance reached the 80%
174 threshold of accuracy, so we only used 26 fields of 2016 for the RF-grassland model.

175 For each field, we constructed a training and a validation data set by visually

176 interpreting randomly selected objects: in each field we assigned ≥ 100 objects to damage, 100
177 to crop (maize or grass), 100 to bare soil (for maize fields only, to differentiate damage from
178 bare soil between maize rows), and 100 objects to undamaged areas shaded by nearby trees
179 (for grasslands only and only if shadow was present in the orthophoto; in these cases, we also
180 included sufficient damaged objects in the shaded area to incorporate the difference between
181 shaded and unshaded damage). In total, we assigned 5,292 objects to maize, 3,802 to damage,
182 and 5,048 to soil in the 32 maize fields. In the 26 grasslands, we allocated 3,700 objects to
183 grass, 3,126 to damage, and 373 to shadow. Subsequently, we used 70% of these objects for
184 training the RF-model. We derived variable importance for each attribute, expressed by MDA
185 (Mean Decrease in Accuracy, Excel Table S2, available online in Supporting Information),
186 which is a measure of loss of accuracy when the variable is left out (Cutler et al. 2007).

187 **Validation Measures**

188 To evaluate the accuracy of the model-deduced damage maps, we used 3 types of validation
189 measures (Fig. 3). We grouped the categories maize and soil (for maize fields), and grass and
190 shadow (for grasslands), in the single category ‘no damage’ because their individual
191 accuracies were not of interest to the study. This allowed for a binary accuracy assessment of
192 ‘damage’ versus ‘no damage.’

193 *Validation of the model.*—We used the remaining 30% of the labeled objects (i.e.,
194 other than the 70% training set) for validation of each model. We calculated a confusion
195 matrix with a set of accuracy measures corrected for object area using the binary assignment.
196 The accuracy measures include user’s accuracy, which is the area of correctly classified
197 objects of a class divided by the total area of predicted objects in a class; producer’s accuracy,
198 which is the area of correctly classified objects of a class divided by the total area of reference
199 objects in a class; and, overall accuracy and the kappa coefficient, which is a measure of how
200 well the model performed compared with performance by chance (Cutler et al. 2007).

201 *Performance as a crop-damage assessment tool.*—We assessed the value of the model
202 for its practical application to evaluate damage for newly collected field imagery by testing its
203 performance on all fields not used for model construction. We manually assigned ≥ 50 objects
204 on each of these independent fields to 1 of 3 possible classes (i.e., damage, crop, soil in maize
205 fields; and damage, crop, shadow in grasslands). We then used this set of objects to validate
206 the RF-models. We set up a confusion matrix and we calculated the same accuracy measures
207 as mentioned corrected for object area size.

208 *Ground-truthing.*—We provided a third validation measure by a ground-truthing
209 check. In 10 maize fields and 10 grasslands photographed in 2017, we took 10 GPS locations
210 for damage and 10 GPS locations for undamaged crop (maize or grass) using a Trimble
211 advanced RTK R6 (Trimble, Sunnyvale, CA; 0.012-m horizontal accuracy on average) on the
212 same day that we photographed the field. This resulted 400 ground-truthing points. We
213 overlaid these GPS locations with the corresponding object after segmentation and
214 classification of the orthophoto by the RF-model. Based on this comparison, we set up a third
215 confusion matrix and we calculated accuracy measures (not based on area calculations but on
216 presence–absence of damage).

217 *Assessment of damaged area.*—Using accuracy measures of corresponding model
218 classes, we could calculate damaged area and damaged percentage of a field (Fig. 4). The
219 error on these calculations involved both user’s and producer’s accuracy of the objects
220 classified as damage and was calculated in 2 steps. First, we calculated the true positive rate
221 (TPR) of damaged area (percentage of damaged area that were correctly classified as
222 damaged) by multiplying damaged area by the user’s accuracy (UA; $TPR = \text{area} \times UA$).
223 Secondly, we corrected the damaged area for the false negative rate (FNR) using the
224 producer’s accuracy (PA): percentage of damage area which was probably missed ($FNR =$
225 $1/PA$). The error is thus calculated using the following formula:

226
$$\text{Error} = \text{TPR} \times \text{FNR}$$

227 **RESULTS**

228 **Validation and Performance of the Model**

229 *Maize fields.*—Model validation (i.e., 30% of objects of the fields used for model
230 construction) showed a high overall accuracy of 96.45%, whereas the model performance
231 with an accuracy of 84.50% shows that classification is more difficult for fields not used for
232 model construction (Table 1). However, ground-truthing showed 94.50% overall accuracy for
233 the constructed RF-model.

234 *Grasslands.*—In the final RF-model for grasslands, 26 orthophotos of 2016 were used
235 (model performance exceeded an overall accuracy of 80% only using fields of 2016).

236 For grasslands, model validation shows an overall accuracy of 95.71% and model
237 performance resulted in an accuracy of 94.40% (Table 2). Ground-truthing showed 98.00%
238 accuracy.

239 **Crop Damage Assessment**

240 The average damaged area (see Fig. 5 for examples) was 17.2% in maize fields and 20.6% in
241 grasslands (Table 3). Using corresponding accuracy measures, the error on damaged area
242 could be calculated as well as the error on the damaged percentage of a field (Excel Table S3,
243 available online in Supporting Information).

244 In terms of time- and cost-efficiency of our drone method, we made a comparison
245 (Table 4) with ground-based estimations as applied in Wallonia (southern Belgium; J. Widar,
246 Fourrages Mieux, personal communication). Start-up costs for our presented drone method
247 are lower than the method of ground-based estimations (Table 4). The labor time for a field
248 visit and damage processing varies widely depending on the accuracy of ground-based
249 estimation (from 90 min for an estimation of 10% of a damaged field of 5 ha to nearly 26 hr
250 for a full exhaustive assessment), whereas the labor time and accuracy is fixed using the drone

251 method (150 min for the same field).

252 **DISCUSSION**

253 Our presented method applies machine learning using GEOBIA on UAV imagery of damaged
254 drop fields by wild boar to calculate damaged area, which is shown to be an objective, time-
255 efficient, and accurate approach. Model performance showed high overall accuracies, with
256 greater accuracies for grasslands than for maize fields. We consider the presented method to
257 be useful as a tool to get a detailed and objective estimation of damaged areas in maize and
258 grasslands.

259 To reach an acceptable model performance of >80% (as an arbitrary limit we set), we
260 needed to combine maize field data from several years, indicating a larger variation among
261 maize fields. Including fields from >3 years might improve model performances for damaged
262 maize fields substantially. Given the high accuracy for grasslands, the expected gain when
263 adding grasslands for >1 year seems not sufficiently advantageous compared with the
264 required time investment.

265 We applied our method to maize and grasslands because we did not have sufficient
266 reported damage cases for other crops. As long as damage is visually distinguishable in aerial
267 photographs (Blaschke 2010, Addink et al. 2012), we are confident that our method can be
268 applied to other crops such as wheat, oats, etc. Michez et al. (2016) pointed out that object-
269 based image analysis improved their classification method in which they used digital
270 elevation models and height thresholds to distinguish damaged from undamaged crops. We
271 studied damage from wild boar (ground check in all cases), but other damage causes do exist,
272 such as those caused by other wildlife species (e.g., badger [*Meles meles*]). These sources of
273 damage can have similar visual characteristics in aerial photographs and might be
274 distinguishable by our GEOBIA-RF model as well. We did not have any cases of damage by
275 other species, so we could not check this nor the possibility to distinguish damage sources.

276 In the assessed maize fields we found that, on average, 17.2% of the area in fields was
277 damaged, whereas in grasslands this figure was 20.6%, although a large variation was found
278 for both crops. Bueno et al. (2010) reported 16% of the assessed area in damaged livestock
279 pastures in Spain to be uprooted (plants pulled out of soil), Engeman et al. (2016) found
280 between 11.2% and 13.5% of the damaged grasslands in Romanian mountains to be rooted.
281 Bueno et al. (2009) reported up to 12% of the total areas of damaged Pyrenean alpine and
282 subalpine grasslands to be actually damaged.

283 Using local crop prices (average yield (euro [€]/ha) over the period 2013–2017 in
284 Flanders, prices according to local farmers' union Boerenbond), direct yield losses in maize
285 fields would be on average 342€/ha of maize field and 282€/ha of grassland. However, this is
286 only a rough estimate because regional and year-dependent yield differences are not taken
287 into account. Moreover, economic losses to farmers are likely greater than merely yield
288 losses. For example in grasslands, uneven surfaces as a result of wild boar rooting may cause
289 damage to mowing machines and restoration measures are needed to repair the damaged
290 grassland (Frederik 1998).

291 The economic effect of damage is the main limiting factors in stakeholders' tolerance
292 toward wildlife (Carpenter et al. 2013). Compensation schemes may increase tolerance of
293 wildlife and promote more positive attitudes toward concerns and therefore decrease the
294 number of human–wildlife conflicts (Nyhus et al. 2005). However, often there is little
295 quantitative evidence and costs are mostly estimated (Nyhus et al. 2003, 2005). When
296 comparing labor time of ground-based estimations with our drone method, we see that time
297 use depends on the accuracy of the ground-based estimation. Start-up costs seem accountable
298 to us when compared with figures like our reported cost per hectare, given that our study area
299 was >330 ha, and the reported damage costs in Europe alone is approximately 80 million
300 euros annually (Putman and Apollonio 2014).

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456

457 **SUPPORTING INFORMATION**

458 Additional supporting material may be found in the online version of this article at the
459 publisher's website.

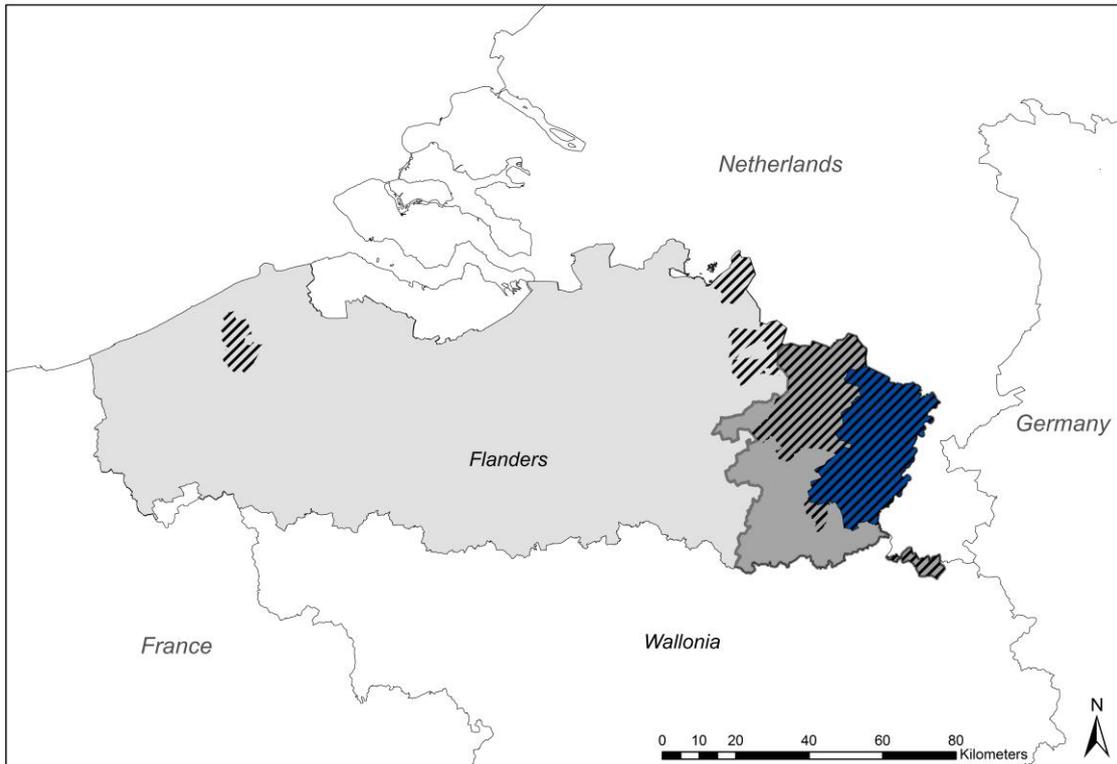
460 Excel Table S1. Overview of fields and photos crop field damaged by wild boar,
461 photographed via drone between 2015 and 2017 in the study area in Flanders (northern part of
462 Belgium).

463 Excel Table S2. Mean decreasing accuracies of Random Forest (RF) algorithm based on a set
464 of 25 attributes describing shape (4), texture (8), and spectral properties (13) of the objects of
465 segmented photos of damaged fields by wild boar, photographed via drone between 2015 and
466 2017 in the study area in Flanders (northern part of Belgium).

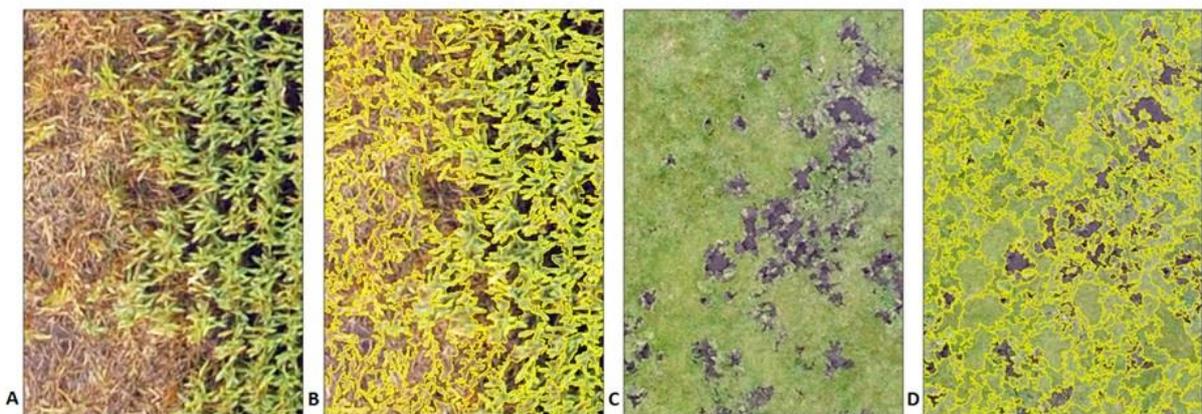
467 Excel Table S3. Damaged area calculations using the resulting Random Forest model of
468 damaged fields by wild boar, photographed via drone between 2015 and 2017 in the study
469 area in Flanders (northern part of Belgium)..

470 **Summary for online Table of Contents:** We used drones, Geographic Object-Based Image
471 Analysis and Random Forest models to assess crop damage by wild boar.

472 **FIGURE CAPTIONS**

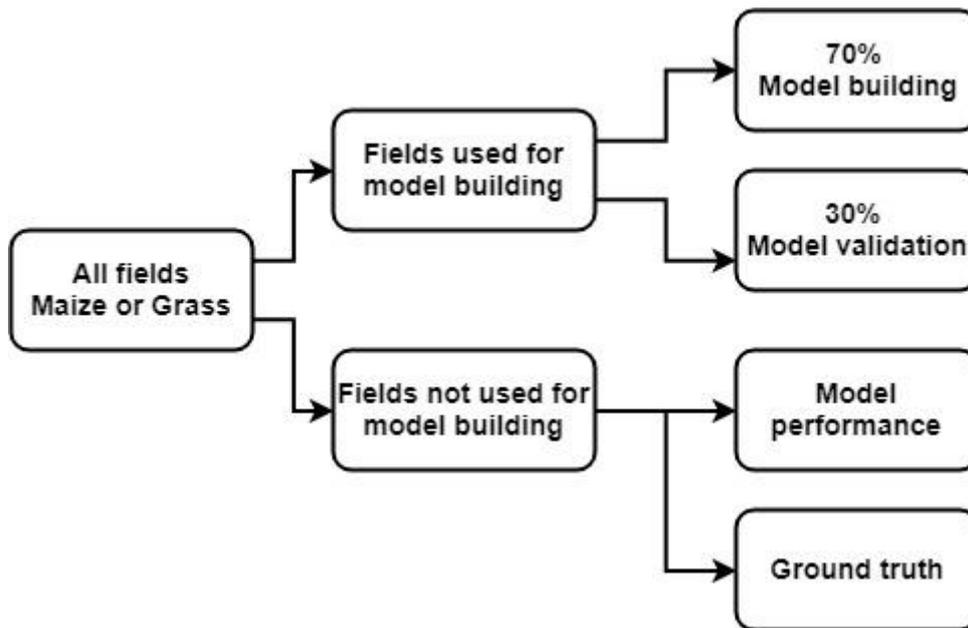


473
 474 Figure 1. Location of study area (blue) in the province of Limburg (dark grey) and Flanders
 475 (northern part of Belgium , light grey) in which 133 crop fields damaged by wild boar have
 476 been photographed via drone between 2015 and 2017. Dashed areas: distribution area of wild
 477 boar in Flanders in 2014.

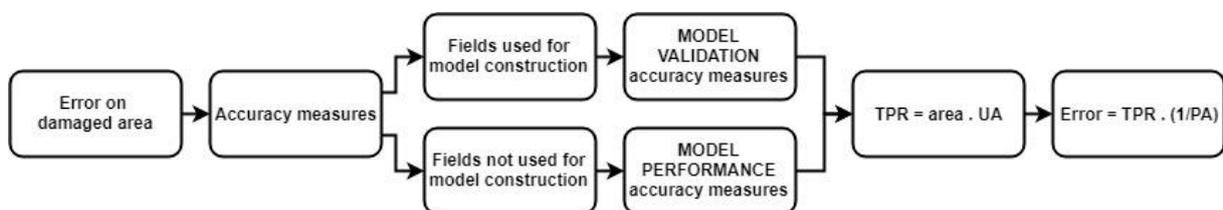


478
 479 Figure 2. Illustration of segmentation (using eCognition) of a crop field damaged by wild
 480 boar, photographed via drone between 2015 and 2017 in the study area in Flanders (northern
 481 part of Belgium). Segmentation of orthophotos of damaged fields is the first step in

482 Geographic Object-Based Image Analysis (GEOBIA) in which pixels are grouped in
 483 homogeneous objects using multiresolution segmentation. Left: Maize field orthophoto
 484 derived from drone photographs (A) and with segments outlined derived from the eCognition
 485 software (B). Right: Grassland orthophoto derived from drone photographs (C) and with
 486 segments outlined derived from the eCognition software (D).



487
 488 Figure 3. Workflow used for the calculation of the accuracy measures of the damaged area,
 489 which is derived from Geographic Object-Based Image Analysis (GEOBIA) and Random
 490 Forest models, to estimate the damaged area in 133 crop fields damaged by wild boar, which
 491 were photographed via drone between 2015 and 2017 in Flanders (northern part of Belgium).



492
 493 Figure 4. Workflow for calculating the error on damaged area, which is derived from
 494 Geographic Object-Based Image Analysis (GEOBIA) and Random Forest models, to estimate
 495 the damaged area in 133 crop fields damaged by wild boar, which were photographed via
 496 drone between 2015 and 2017 in Flanders (northern part of Belgium). The error on the

497 damaged area is calculated using accuracy measures of corresponding classes (model
498 validation or model performance), true positive rate (TPR), user's accuracy (UA), and
499 producers' accuracy (PA).



500
501 Figure 5. Visualization of the resulting Geographic Object-Based Image Analysis (GEOBIA)
502 Random-Forest model classification of the area damaged by wild boar (yellow) in a maize
503 field (A = original field, B = classified damage) and grassland (C = original field, D =
504 classified damage) as 1 of the 133 crop fields damaged by wild boar photographed via drone
505 between 2015 and 2017 in Flanders (northern part of Belgium).

506

507

508

509 **TABLES**

510 Table 1. Confusion matrices (a = area [m² and between brackets: *n* = no. of objects) and
 511 accuracy measures (corrected for object area) for the Random Forest model for assessing
 512 maize fields damaged by wild boar, for which 79 damaged maize fields were photographed
 513 via drone between 2015 and 2017 in Flanders (northern part of Belgium), and a Geographic
 514 Object-Based Image Analysis and Random Forest model was developed.

Model validation, a =

Reference

91.20 m²

(*n* = 4,243 objects)

Predicted	Damage	No damage	User's accuracy (%)
Damage	29.62 (1,065)	1.53 (70)	95.10
No damage	1.71 (76)	58.35 (3,032)	97.16
Producer's accuracy (%)	94.55	97.45	
Overall accuracy (%)	96.45		
Kappa coeff.	0.92		

Model performance, a =

Reference

39.19 m²

(*n* = 2,422 objects)

Predicted	Damage	No damage	User's accuracy (%)
Damage	21.52 (990)	1.82 (135)	92.21

No damage	4.26 (151)	11.60 (1,146)	73.16
Producer's accuracy (%)	83.49	86.45	
Overall accuracy (%)	84.50		
Kappa coeff.	0.67		

515

Ground-truth	Reference		
<i>(n = 200 objects)</i>			
Predicted	Damage	No damage	User's accuracy (%)
Damage	95	6	94.06
No damage	5	94	94.95
Producer's accuracy (%)	95.00	94.00	
Overall accuracy (%)	94.50		
Kappa coeff.	0.89		

516

517

518 Table 2. Confusion matrices (a = area [m²] and between brackets: *n* = no. of objects) and
 519 accuracy measures (corrected for object area) for the Random Forest model for assessing
 520 damaged grasslands by wild boar, for which 54 damaged grasslands were photographed via
 521 drone between 2015 and 2017 in Flanders (northern part of Belgium), and a Geographic
 522 Object-Based Image Analysis and Random Forest model was developed.

Model validation, a =	Reference		
92.54 m ²			
(<i>n</i> = 2,160 objects)			

Predicted	Damage	No damage	User's accuracy (%)
Damage	21.45 (857)	1.86 (64)	92.03
No damage	2.12 (81)	67.12 (1,158)	96.94
Producer's accuracy (%)	91.03	97.31	
Overall accuracy (%)	95.71		
Kappa coeff.	0.89		

523

Model performance, a =	Reference		
47.23 m ²			
(<i>n</i> = 1,245 objects)			

Predicted	Damage	No damage	User's accuracy (%)
Damage	10.44 (515)	1.00 (72)	91.24

No damage	1.64 (75)	34.15 (658)	95.40
Producer's accuracy (%)	86.39	97.15	
Overall accuracy (%)	94.40		
Kappa coeff.	0.85		

524

Ground-truth Reference

(*n* = 200 objects)

Predicted	Damage	No damage	User's accuracy (%)
Damage	99	1	99.00
No damage	3	97	97.00
Producer's accuracy (%)	97.01	98.90	
Overall accuracy (%)	98.00		
Kappa coeff.	0.96		

525

526

527 Table 3. Average percent damaged area within a field (with min. and max.) over all 133 fields
 528 damaged by wild boar, which were photographed via drone between 2015 and 2017 in
 529 Flanders (northern part of Belgium), as derived from a Geographic Object-Based Image
 530 Analysis and Random-Forest model classification that was developed.

Crop		No. of fields	Average percent damaged (min.–max.)
Maize	2015	21	16.50 (0.83–44.89)
	2016	26	12.70 (0.36–45.11)
	2017	32	22.40 (2.09–52.87)
	Total	79	17.20
Grass	2015	1	19.00
	2016	33	19.10 (3.98–87.77)
	2017	20	24.00 (4.11–48.82)
	Total	54	20.60

531

532 Table 4. Overview of costs and time requirement involved in damage assessment of fields damaged by wild boar during 2015 and 2017 using the
 533 presented drone method or ground visit like done in Wallonia (southern part of Belgium, J. Widar, Fourrages Mieux, personal communication),
 534 in which often only a part of the fields is estimated depending on the intensity of the damage. Hourly wages are not included as these can be
 535 variable. Passive processing time is not included as this does not influence active labor time. € = euros.

Drone		Ground visit	
Start-up costs			
ENVI Onebutton license:	€890	Estimation software development:	€25.000
Agisoft Photoscan Pro license:	€2.900		
eCognition license:	€1.716		
DJI Phantom 3:	€1.200		
Sufficient batteries for a full day field assessments	€1.500		
Total cost	€8.206	Total cost	€25.000
Field visit			
Photographing field	5 min/ha	Ground assessment	Surveying 10%: 15 min/ha Surveying 20–25%: 30 min/ha

Full exhaustive assessment: 5 hr
and 6 min/ha

Data processing

1)	Stitch photo's	Average	Applying estimation software	15 min/field
2)	Segment photo's	processing labor		
3)	Apply RF-model	time: 2 hr/field		
Total field of 5 ha		2 hr 30 min	Total field of 5 ha	From 1 hr 30 min to 25 hr 45 min

536

537